

---

# Overview of UP-Fall Detection Project

---

Anonymous Author(s)

Affiliation

Address

email

## Abstract

1 In this paper, we present an overview of our project of UP-Fall Detection. The  
2 aim of this project is to configure a simple, comfortable and fast fall detection  
3 and human activity recognition system. This system must be accurate in fall  
4 detection and easy to implement and adopt. We briefly describe the achievements  
5 and advances obtained in two years.

## 6 1 Introduction

7 Fall prevalence has increased in recent years due to the world phenomenon of population aging [1].  
8 Falls are actually considered a major health problem in the world [2] given that falls often cause  
9 severe injuries and death mainly among elderly persons. Reliable and robust fall detection systems are  
10 needed in order to reduce the time in which a person receives medical attention when a fall occurs and  
11 diminish its negative consequences. Main approaches of human activity recognition, fall classification  
12 and fall detection systems use wearable devices, ambient sensors and/or vision devices[3]. There  
13 are important challenges and issues reported by most authors like privacy concerns, obtrusiveness  
14 and operative device limitations, and difficulty of comparison among techniques caused by the lack  
15 of public databases. Other frequent design challenges when developing a fall detection system are  
16 selecting which modality of sensor to use for data acquisition; determine the best placement and  
17 orientation of the information sources; and selecting the most suitable fall detection technique.

18 In this paper, we present an overview of our project of UP-Fall Detection. The aim of this project  
19 is to configure a simple, comfortable and fast fall detection and human activity recognition system.  
20 This system must be accurate in fall detection and easy to implement and adopt. We briefly describe  
21 the achievements and advances obtained in these two years in which the aforementioned challenges  
22 were addressed.

23 This project is an initiative of Computer Intelligence and Vision (INVICO) research group at Uni-  
24 versidad Panamericana to build an ambient assisted living monitoring system for elder people. The  
25 aforementioned system's goals are:

- 26 1) The creation of a monitoring system that allows the independence of older adults to be maintained  
27 and improves their well-being and safety conditions. This system will focus on using using different  
28 combinations of vision, wearables and ambient sensors to gain more precision and robustness as well  
29 as machine learning techniques to provide assistance, in a first stage, when there are falls.
- 30 2) Identify the severity of the damage caused by the fall by monitoring your breathing without  
31 intrusive contact sensors, using a vision system.

## 32 2 UP-Fall Detection Project Overview

33 The project is divided into two phases: (1) database creation, (2) data analysis and system simplifica-  
34 tion. We describe each part of the project in this section.

Table 1: Ranking (top-bottom) of the best IMU sensor per classifier, based on F-score

IMU type				
	RF	SVM	MLP	KNN
1	(98.36) Waist	(83.30) Right Pocket	(57.67) Right Pocket	(73.19) Right Pocket
2	(95.77) Neck	(83.22) Waist	(44.93) Neck	(68.73) Waist
3	(95.35) Right Pocket	(83.11) Neck	(39.54) Waist	(65.06) Neck
4	(95.06) Ankle	(82.96) Ankle	(39.06) Left Wrist	(58.26) Ankle
5	(94.66) Left Wrist	(82.82) Left Wrist	(37.56) Ankle	(51.63) Left Wrist

### 35 2.1 Database creation: UP-Fall Detection Dataset

36 In previous work, [4] we present a publicly available multimodal dataset for fall detection in order  
 37 to address the problem of lack of available datasets for comparison among fall detection systems  
 38 and machine learning techniques. UP-Fall Detection dataset was collected over 17 healthy young  
 39 subjects using multiple modalities. The volunteers performed three attempts each of six daily  
 40 living activities, and simulated five different types of fall. We use five wearable sensors to collect  
 41 accelerometer, gyroscope and ambient light data. These sensors were positioned in the left wrist, in  
 42 the neck, at right pocket of pants, in the belt, and left ankle. In addition, we acquired data from one  
 43 electroencephalograph (EEG) headset, six infrared sensors, and two cameras. This dataset comprises  
 44 raw and feature sets summarizing information from wearable sensors, ambient sensors and vision  
 45 devices. The aim of our dataset is to leverage fair comparisons of fall detection solutions. It also  
 46 provides many experimental possibilities for the signal and human activity recognition, vision, and  
 47 machine learning community. The consolidated dataset (812 GB), as well as, the feature dataset (171  
 48 GB) are publicly available in <http://sites.google.com/up.edu.mx/har-up/>.

### 49 2.2 A Comparison Analysis for Best Multimodal Combination Devices in a Fall Detection 50 System

51 There are different approaches of fall detection system and their success depend on the types of  
 52 devices selected for data acquisition, the location in which these devices are placed, and how fall  
 53 detection is done. We designed experiments in order to determine the best suited placement and  
 54 multimodal combination and simplify the system improving fall detection efficiency and precision.  
 55 We mainly focus on the best choice of a wearable sensor and a camera viewpoint. In the analysis  
 56 over the UP-Fall Detection data set, we built an independent classifier model (random forest (RF),  
 57 multilayer perceptron (MLP) and k-nearest neighbors (KNN), support vector machines (SVM) ) for  
 58 each window-length feature data set for each IMU sensor.

59 We summarized the ranking of the IMU sensors per performance classifier, based on the F-score,  
 60 obtained from the previous results in table 1. The best performance is obtained using the following  
 61 isolated IMU sensors: waist, neck and right pocket (i.e. the IMU types in the shadowed region).  
 62 Also, ankle and left wrist IMU sensors performed the worst. In addition, the combination of the IMU  
 63 sensors and the cameras was also important in this task.

### 64 2.3 Publicly available resources

65 Another contribution is a public repository with many Python programs for feature selection, training  
 66 and validation. Features were calculated using three different time-windows with overlap. Available  
 67 in <https://github.com/jpnm561/HAR-UP>.

## 68 3 Conclusions

69 We presented the achievements obtained in UP-Fall detection project. We are now working towards  
 70 an assisted daily life monitoring system using mobile technologies, less intrusive and low cost. The  
 71 social contribution is to relieve the burden of caregivers and family members who care for older  
 72 adults and increase their safety.

73 **Acknowledgments**

74 This research has been funded by Universidad Panamericana through the grants “Fomento a la  
75 Investigación UP 2017 and 2018”, under project codes UP-CI-2017-ING-MX-02 UP-CI-2018-ING-  
76 MX-04.

77 **References**

78 [1] Population Division United Nations, D. o. E. a. SA. World population prospects: The 2017  
79 revision, key findings and advance tables”. 2017.

80 [2] World Health Organization et al. Who global report on falls prevention in older age. 2007. *World*  
81 *Health Organization*, pages 1–7, 2015.

82 [3] Muhammad Mubashir, Ling Shao, and Luke Seed. A survey on fall detection: Principles and  
83 approaches. *Neurocomputing*, 100:144–152, 2013.

84 [4] Lourdes Martínez-Villaseñor, Hiram Ponce, Jorge Brieva, Ernesto Moya-Albor, José Núñez-  
85 Martínez, and Carlos Peñafort-Asturiano. Up-fall detection dataset: a multimodal approach.  
86 *Sensors*, 19(9):1988, 2019.